## Policy Fairness in Sequential Allocations under Bias Dynamics

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Model: Markov Decision Process (MDP)

Population partitioned based on constant affiliation with constant group sizes

Decision maker (DM)

1. Takes <u>action</u>: sets admission thresholds  $\theta_A$ ,  $\theta_D$ 

one for each group, admits a constant fraction of the population

Advantaged group (A): success probability = ability

Disadvantaged group (D): success probability ≤ ability

State (s): current bias (upper bound of the success distribution of D)



**Utility Maximizing Policy** 

- Optimization: Policy Iteration (infinite horizon, discrete state space) No fairness constraints
- Both policies apply preferential treatment (PT), but in different ways
- The effect of affirmative action on long-term fairness strongly depends on the dynamics

2. Receives <u>reward (R)</u>: fraction of successful students Goal: maximizing utility (U, discounted sum of rewards)  $U = \sum_{t} \gamma^{t} R_{t}$ <u>Transition function</u>: bias dynamics - **Representation dynamics** - fraction of selected students from D - **Relative success dynamics** - success probability of admitted

students from D





Fairness-Utility Trade-off -

**Representation Dynamics** 

**Relative Success Dynamics** 

Discount factor:

larger values place more weight on the future

- When observing immediate reward and bias(after 1 step), it appears as if there is a fairness-utilitytrade-off, dependent on the discount factor.
- Yet, fairness and utility are aligned in the long-term, the trade-off is between short-term and long-term <sup>L</sup> t rewards



Future Work

**Facing Uncertainty** 

In reality we do not know the bias dynamics



MDP with **unknown transition function** 

## Method

Learn transition function using Bayesian Linear Regression

Learn optimal policy under current belief using Policy Gradient



